



# Geometric ergodicity in Wasserstein distance of a Metropolis algorithm based on a first-order Euler exponential integrator

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- 1 Introduction to Markov Chain Monte Carlo methods
  - Motivations
  - Some Markov chain theory
  - The Metropolis-Hastings algorithm
  - Uniform ergodicity of the independent sampler
  - Symmetric Random Walk Metropolis
  
- 2 Geometric ergodicity in Wasserstein distance and application
  - Geometric ergodicity in Wasserstein distance
  - Application to the EI-MALA

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## Bayesian setting (I)

- Let  $(E, d)$  be a Polish space endowed with its  $\sigma$ -field  $\mathcal{B}(E)$ .
- In a Bayesian setting, a parameter  $x \in E$  is embedded with a **prior distribution**  $\pi$  and the observations are given by a **probabilistic model** :

$$Y \sim \ell(\cdot|x)$$

The inference is then based on the **posterior distribution** :

$$\pi(dx|Y) = \frac{\pi(dx)\ell(Y|x)}{\int \ell(Y|u)\pi(du)}.$$

In most cases the normalizing constant is **not tractable** :

$$\pi(dx|Y) \propto \pi(dx)\ell(Y|x).$$

## Bayesian setting (II)

Bayesian decision theory relies on minimization problems involving expectations :

$$\int_E L(x, \theta) \ell(Y|x) \pi(dx)$$

Generic problem : estimation of an expectation  $\mathbb{E}_\pi[f]$ , where

- $\pi$  is known up to a multiplicative factor ;
- we do not know how to sample from  $\pi$  (no basic Monte Carlo estimator) ;
- $\pi$  is high dimensional density (usual importance sampling and accept/reject inefficient).

## Key tool : the rejection sampling

In the case  $E = \mathbb{R}^d$ , and  $\pi$  has a density with respect to the Lebesgue measure  $\text{Leb}^d$ , also denoted  $\pi$ .

Assume we know that  $\pi(x) \leq M\nu(x)$  and that we know how to sample from  $\nu$ .

1. Sample  $X \sim \nu$  and  $U \sim U([0, 1])$ .
2. If  $U \leq \frac{\pi(X)}{M\nu(X)}$ , accept  $X$ .
3. Else go to 1.

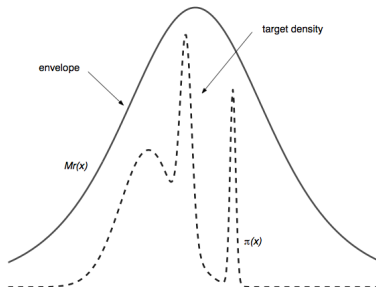


FIGURE: \*

Illustration of the Accept-Reject method [Cappé, Moulines, Ryden 2005].

## Inefficiency of the rejection sampling

- Hard to find a probability  $\nu$  such that  $\pi \leq M\nu$  (especially for **high dimensional settings**).
- On one hand  $M^{-1}$  is the **rate of acceptance** so that  $M$  has to be **as close to 1 as possible**.  
But on the other hand, in practice  $M$  **is exponentially large in the dimension**.

**Alternative** : MCMC method !



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## Some Markov chain theory (I)

## Definition

Let  $P : E \times \mathcal{B}(E) \rightarrow \mathbb{R}_+$ .  $P$  is a Markov kernel if

- for all  $x \in E$ ,  $A \mapsto P(x, A)$  is probability measure on  $E$ ,
- for all  $A \in \mathcal{B}(E)$ ,  $x \mapsto P(x, A)$  is measurable from  $E$  to  $\mathbb{R}$ .

## Some Markov chain theory (II)

## Some simple properties :

- If  $P_1$  and  $P_2$  is two Markov kernel, we can define a new Markov kernel, denoted  $P_1 P_2$ , by for all  $x \in E$  and  $A \in \mathcal{B}(E)$  :

$$P_1 P_2(x, A) = \int_E P_1(x, dz) P_2(z, A) .$$

- If  $P$  is a Markov kernel and  $\nu$  a probability measure on  $E$ , we can define a probability measure, denoted  $\nu P$ , by for all  $A \in \mathcal{B}(E)$  :

$$\nu P(A) = \int_E \nu(dz) P(z, A) .$$

- Let  $P$  be a Markov kernel on  $E$ . For  $f : E \rightarrow \mathbb{R}_+$  measurable, we can define a measurable function  $Pf : E \rightarrow \mathbb{R}_+$  by

$$Pf(x) = \int_E P(x, dz) f(z) .$$

## Some Markov chain theory (III)

**Invariant probability measure** :  $\pi$  is said to be an invariant probability measure for the Markov kernel  $P$  if  $\pi P = \pi$ .

**Theorem** (Meyn and Tweedie, 2003, Ergodic theorem)

*With some conditions on  $P$ , we have for any  $f \in L^1(\pi)$ ,*

$$\hat{\pi}(f) = \frac{1}{n} \sum_{i=1}^n f(X_i) \xrightarrow{\pi\text{-a.s.}} \int f(x) \pi(dx).$$

## Conditions of the Theorem

## Definition

- **Irreducibility** : there exists a measure  $\nu$  such that, for all  $x$  and all  $A$  such that  $\nu(A) > 0$ , there exists  $n \in \mathbb{N}^*$  s.t.  $P^n(x, A) > 0$ .
- **Harris recurrence** :  $P$  is Harris recurrent : for all  $A \in \mathcal{B}(E)$  satisfying  $\pi(A) > 0$ , for all  $x$  in  $A$

$$\mathbb{P} \left[ \sum_{k=1}^{+\infty} \mathbb{1}_A(X_k) = +\infty \mid X_0 = x \right] = 1 .$$

## MCMC : rationale (I)

The Theorem above gives the following idea to approximate  $\mathbb{E}_\pi[f]$  :

- Find a kernel  $P$  with invariant measure  $\pi$ , from which we can efficiently sample.
- Sample a Markov chain  $X_1, \dots, X_n$  with kernel  $P$  and compute

$$\hat{\pi}(f) = \frac{1}{n} \sum_{i=1}^n f(X_i)$$

to approximate  $\mathbb{E}_\pi[f] = \int f(x)\pi(dx)$ .

⇒ How to find a Markov kernel  $P$  with invariant measure  $\pi$  ?

Simple condition to check that  $\pi$  is invariant for  $P$  : **reversibility**.

### Definition

$P$  is reversible with respect to  $\pi$  if for all  $A_1, A_2 \in \mathcal{B}(E)$  :

$$\int_{A_1} \int_{A_2} \pi(dz_1) P(z_1, dz_2) = \int_{A_1} \int_{A_2} \pi(dz_2) P(z_2, dz_1) .$$

- Note the variables  $z_1$  and  $z_2$  are switched.
- For  $A_1 = E$  and  $A_2 = A$ , we get  $\pi(A) = \pi P(A)$ .

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## The Metropolis-Hastings algorithm (I)

The Metropolis-Hastings algorithm gives a generic method to build Markov kernels  $P$  reversible w.r.t.  $\pi$  in the case where :

- $E = \mathbb{R}^d$ .
- Objective target probability  $\pi$  has a density w.r.t.  $\text{Leb}^d$ , also denoted  $\pi$ .

Using of a transition density  $q(x, y)$  w.r.t.  $\text{Leb}^d$  :

- $(x, y) \mapsto q(x, y)$  is measurable,
- For all  $x, y \mapsto q(x, y)$  is a density of a probability measure also denoted  $q(x, \cdot)$ .

## The Metropolis-Hastings algorithm (II)

Given  $X_k$ ,

1. Generate  $Y_{k+1} \sim q(\cdot, X_k)$ .

2. Set

$$X_{k+1} = \begin{cases} Y_{k+1} & \text{with probability } \alpha(X_k, Y_{k+1}), \\ X_k & \text{with probability } 1 - \alpha(X_k, Y_{k+1}). \end{cases}$$

where

$$\alpha(x, y) = 1 \wedge \frac{\pi(y)}{\pi(x)} \frac{q(y, x)}{q(x, y)}.$$

- With this choice of  $\alpha$  the algorithm produces a Markov kernel  $P_{MH}$  reversible w.r.t.  $\pi$ .
- “No restriction” on  $\pi$  and  $q$ .

## MH : properties

Simple condition to apply the Ergodic theorem :

- $q$  and  $\pi$  are **continuous**.
- For all  $x, y$  such that  $\pi(y) > 0$ ,

$$q(x, y) > 0.$$

**Consequence :**

For any  $f \in L^1(\pi)$ ,

$$\hat{\pi}(f) = \frac{1}{n} \sum_{i=1}^n f(X_i) \xrightarrow[a.s.]{} \int f(x) \pi(x) dx.$$

Question : can we have **a rate of convergence** for some  $f$  ?

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## Total variation distance

## Definition

For  $\mu, \nu$  two probabilities measure on  $E$ , the total variation distance between  $\mu$  and  $\nu$  is given by

$$\begin{aligned} W_{d_0}(\mu, \nu) &= \inf_{A \in \mathcal{B}(E)} |\mu(A) - \nu(A)|, \\ &= \sup_{|f| \leq 1} |\mathbb{E}_\mu[f] - \mathbb{E}_\nu[f]|. \end{aligned}$$

- Convergence in total variation distance implies **the weak convergence**.
- Convergence rates in total variation distance imply **convergence rates for  $\mathbb{E}_{\mu_n}[f]$** .

## Uniform ergodicity

### Definition

Let  $P$  be a Markov kernel on  $E$ , with invariant measure  $\pi$ .  $P$  is uniformly geometrically ergodic if there exists  $C < +\infty$ , and  $\rho \in (0, 1)$  such that for all  $x \in E$  :

$$W_{d_0}(P^n(x, \cdot), \pi) \leq C\rho^n.$$

### Theorem (Meyn and Tweedie, 2003)

When  $P$  satisfy a technical condition (aperiodicity),  $P$  is uniformly geometrically ergodic if and only if there exist  $\delta, \epsilon \in (0, 1)$ ,  $n \in \mathbb{N}^*$  and a probability measure  $\mu$  such that

$$\forall A \in \mathcal{B}(E), \mu(A) > \delta \Rightarrow \inf_{x \in A} P^n(x, A) > \epsilon.$$

## Uniform ergodicity : the independent case [Hastings 1970] (II)

**Theorem** ([Roberts, Tweedie 1996], [Mengersen, Tweedie 1996])

If *there exists  $M$  such that  $\pi(z) \leq Mg(z)$  then for all  $x \in \mathbb{R}^d$*

$$W_{d_0}(P_{\text{IMH}}^n(x, \cdot), \pi) \leq \left(1 - \frac{1}{M}\right)^n.$$

1. Expected acceptance probability still is  $1/M$ .
2. But **no need to know  $M$**  to run the algorithm !
3. If the **majoration condition does not hold**, no uniform ergodicity.

## Cauchy vs Normal (I) [Cappé, Moulines, Ryden 2005]

- Target distribution :  $\pi(x) \propto (1 + x^2)^{-1}$ .
- Proposal distribution :  $g(y) \sim \mathcal{N}(0, 1)$ .

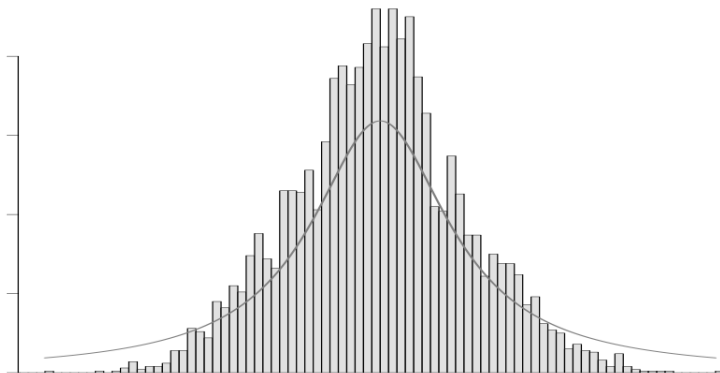


FIGURE: \*

Histogram of IMH with 5000 samples.



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## symmetric Random walk Metropolis-Hastings (I)

- The idea in the RWM is to propose **local moves around the current states** and not moves independent of the position.
- The proposal mechanism is given by

$$Y_{k+1} = X_k + Z_{k+1},$$

where  $Z_{k+1}$  is independent of  $X_k$  and is distributed according to a probability measure with a **symmetric density  $\tilde{q}$** .

- The proposal distribution is **of the form  $q(x, y) = \tilde{q}(y - x)$** .

## symmetric Random walk Metropolis-Hastings (II)

1. Generate  $Z_{k+1}$  from  $\tilde{q}$  and set  $Y_{k+1} = X_k + Z_{k+1}$ .
2. Set

$$X_{k+1} = \begin{cases} Y_{k+1} & \text{with probability } \alpha(X_k, Y_{k+1}), \\ X_k & \text{with probability } 1 - \alpha(X_k, Y_{k+1}). \end{cases}$$

where

$$\alpha(x, y) = 1 \wedge \frac{\pi(y)}{\pi(x)}.$$

## Cauchy vs Normal (II) [Cappé, Moulines, Ryden 2005]

- Target distribution :  $\pi(x) \propto (1 + x^2)^{-1}$ .
- Proposal distribution :  $\mathcal{N}(0, 1)$ .

$$\alpha(x, y) = 1 \wedge \frac{1 + x^2}{1 + y^2}$$

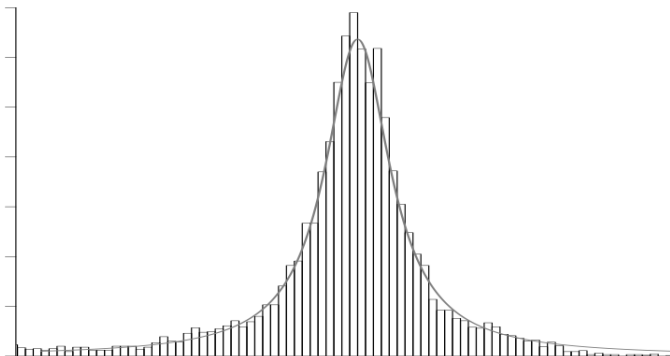


FIGURE: \*

## Another kind of convergence : the geometric ergodicity

1. Using random walk moves prevents from being uniformly geometrically ergodic [Robert, Casella 2004]. But still, we can have geometric ergodicity.
2. The condition  $W_{d_0}(P^n(x, \cdot), \pi)$  was controlled uniformly in  $x$  is relaxed.

## Definition

Let  $P$  be a Markov kernel with invariant probability measure  $\pi$ .  $P$  is **geometrically ergodic** if there exists  $C < +\infty$ ,  $\rho \in (0, 1)$  and a measurable function  $V : E \rightarrow [1, +\infty)$  such that :

$$W_{d_0}(P^n(x, \cdot), \pi) \leq C\rho^n V(x), \quad \forall x \in E.$$

## Conditions to get geometric ergodicity (I)

## Definition

A set  $\mathcal{C} \in \mathcal{B}(E)$  is said to be *m-small* for  $P$  if there exists  $\epsilon > 0$  and a probability measure  $\mu$  such that :

$$\forall A \in \mathcal{B}(E), \quad \inf_{x \in \mathcal{C}} P(x, A) \geq \epsilon \mu(A).$$

## Theorem (Meyn and Tweedie 2003)

Let  $P$  an irreducible Markov kernel satisfying a technical condition (aperiodicity).

$P$  is geometrically ergodic if and only if there exists  $b < +\infty$ ,  $\lambda \in (0, 1)$  and a measurable function  $V : E \rightarrow [1, +\infty)$  such that for all  $x \in E$

$$PV(x) \leq \lambda V(x) + b \mathbb{1}_{\mathcal{C}}(x),$$

where  $\mathcal{C}$  is a *m-small* set for  $P$ .

Geometric ergodicity of the RMH on  $\mathbb{R}$ 

## Theorem (Mengersen and Tweedie, 1994)

Assume that

- $\pi$  is continuous and symmetric on  $\mathbb{R}$ , and log-concave in the tail, ie there exists  $M, a \in \mathbb{R}_{>0}$  such that for all  $|y| \geq |x| \geq M$ ,

$$\log(\pi(x)) - \log(\pi(y)) \geq a|x - y| ,$$

- the transition density of the noise  $\tilde{q}$  is continuous and positive on  $\mathbb{R}$ .

Then,  $P_{\text{RWM}}$  is geometrically ergodic.

The proof follows from the previous theorem applied with  $V(x) = e^{s|x|}$ .

## Issues of the geometrical ergodicity in total variation norm

1. In an infinite dimensional setting, Markov chain will typically be **not irreducible**. So we cannot apply the previous result to this kind of kernel.
2. The contraction coefficient  $\rho$  in the previous theorem is smaller than the constant  $\epsilon$  which appears in the definition of the a small set. Most of the time,  **$\epsilon$  is exponentially small in the dimension**.  
So in high dimensional settings, we can observe poor mixing even if the chain is geometrically ergodic.

In the following, we try to give some solutions to the second point. We consider **another kind of convergence**, which suggests ways to construct sampler with **good mixing rate**, even if the dimension is large.



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## Wasserstein distance (I)

Recall  $(E, d)$  is a Polish space.

We assume in the following that  $d$  is bounded by 1.

### Definition

1. Let  $\mu$  and  $\nu$  two probability measures on  $E$ .  $\lambda$  is a coupling of  $\mu$  and  $\nu$  if  $\lambda$  is a probability on  $E \times E$ , such that for all  $A \in \mathcal{B}(E)$ ,

$$\lambda(A \times E) = \mu(A) \text{ and } \lambda(E \times A) = \nu(A).$$

The set of the couplings of  $\mu$  and  $\nu$  will be denoted  $C(\mu, \nu)$ .

2. The Wasserstein metric associated to  $d$ , between two probability measures  $\mu, \nu$  is defined by :

$$W_d(\mu, \nu) = \inf_{\lambda \in C(\mu, \nu)} \int_{E \times E} d(x, y) d\lambda(x, y),$$

## Wasserstein distance (II)

- We get back the the total variation distance when  $d(x, y) = d_0(x, y) = \mathbb{1}_{x \neq y}$
- The convergence in total variation implies the convergence in Wasserstein distance but the converse is false.
- The convergence in  $W_d$  is equivalent to the weak convergence ; (see e.g. [Villani, 2009] for details).

So, we generalize the use of the total variation distance.

## Coupling set

In the following, we adapt the notion of small set to this setting.

## Definition

Let  $P$  be a Markov kernel on  $E$ . Let  $\blacksquare \in \mathcal{B}(E \times E)$ , and  $\epsilon \in (0, 1)$ .

We say that  $\blacksquare$  is a  $(\epsilon, d)$ -coupling set for the Markov kernel  $P$  if there exists a kernel  $\mathbf{K}$  on  $(E \times E, \mathcal{B}(E \times E))$  satisfying the following conditions

- for all  $x, y \in E$ ,  $\mathbf{K}((x, y), \cdot)$  is a coupling of  $(P(x, \cdot), P(y, \cdot))$ .

- for all  $x, y \in E$ ,

$$\mathbf{K}d(x, y) \leq d(x, y).$$

- for all  $(x, y) \in \blacksquare$ ,

$$\mathbf{K}d(x, y) \leq (1 - \epsilon)d(x, y).$$

If  $\mathcal{C}$  is a 1-small set,  $\mathcal{C} \times \mathcal{C}$  is an  $(\epsilon, d_0)$ -coupling set.

## Quantitative bound for geometric ergodicity in Wasserstein distance

We have the following theorem which generalizes and precises the constants of the theorem about geometric ergodicity in total variation distance.

### Theorem

Let  $P$  be Markov kernel on  $E$  and assume

- There exists a measurable function  $V : E \rightarrow [1, +\infty)$ ,  $\lambda \in [0, 1)$  and  $b < +\infty$  such that for all  $x \in E$ ,

$$PV(x) \leq \lambda V(x) + b.$$

- For some  $\delta > 0$ , the subset

$$\blacksquare \stackrel{\text{def}}{=} \{(x, y) \in E \times E, V(x) + V(y) \leq (2b + \delta)/(1 - \lambda)\},$$

is an  $(\epsilon, d)$ -coupling.

Then  $P$  admits a unique probability measure  $\pi$  and for all  $x \in E$

$$W_d(P^n(x, \cdot), \pi) \leq C\rho^n V(x)$$

where  $C < +\infty$  and  $\rho \in (0, 1)$ , which can be explicitly calculated in function of  $\epsilon, \lambda, b$  and  $\delta$ .

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## Presentation of the EI-MALA (I)

EI-MALA is Metropolis Hasting algorithm, based on the following.

- Let  $\pi$  be the target density and  $\pi_U(x)dx \propto e^{-U(x)} dx$  be an auxiliary probability measures on  $\mathbb{R}^d$ .
- Typically,  $-\log(\pi_U)$  will be a **convex minorant** of  $-\log(\pi)$ . So, we assume that  $U$  is given by

$$U(x) = (1/2)x^T Qx + \blacksquare(x) \text{ with } Q \succ 0.$$

- Consider the **over-damped Langevin SDE associated with  $\pi_U$**  :

$$dY_t = -Y_t dt - Q^{-1} \nabla \blacksquare(Y_t) dt + \sqrt{2} Q^{-1/2} dB_t.$$



## Presentation of the EI-MALA (II)

- A **stochastic Euler exponential integrator** yields to the following discretization for  $h \in (0, 2)$  :

$$\mathcal{O}_h(x, Z_1) = x - (h/2)Q^{-1}\nabla U(x) + \sqrt{h - h^2/4} Q^{-1/2}Z_1 ,$$

where  $Z_1 \sim \mathcal{N}(0, I_d)$ .

- It yields to a **proposal density**  $q_h$  which can be used in a Metropolis-Hastings algorithm.
- Given  $h \in (0, 2)$  and  $X_n$ ,
  - 1 Sample  $Z_{k+1} \sim \mathcal{N}(0, I_d)$  and set  $Y_{k+1} = \mathcal{O}(X_k, h)$ .
  - 2 Set

$$X_{k+1} = \begin{cases} Y_{k+1} & \text{with probability } \alpha_h(X_k, Y_{k+1}), \\ X_k & \text{with probability } 1 - \alpha_h(X_k, Y_{k+1}). \end{cases}$$

where

$$\alpha_h(x, y) = 1 \wedge \frac{\pi(y) q_h(y, x)}{\pi(x) q_h(x, y)} .$$

## Geometric convergence of the EI-MALA (I)

- Denote by  $\|\cdot\|_Q$  the norm on  $\mathbb{R}^d$  associated with the positive definite matrix  $Q$ .
- Using the previous Theorem, we establish the geometric convergence of the EI-MALA algorithm when  $\pi$  is given by  $\pi(x) \propto e^{-(1/2)x^T Q x - \Phi(x) - \Psi(x)}$ , where  $\Phi$  satisfies with  $\Psi$  the following assumptions.

## M1

1. The function  $\Phi$  belongs to  $C^1(\mathbb{R}^d)$ , is convex and there exists  $C_\Phi$  such that for all  $x, y \in \mathbb{R}^d$ ,  $\|Q^{-1}(\nabla\Phi(x) - \nabla\Phi(y))\|_Q \leq C_\Phi \|x - y\|_Q$ .
2. The function  $\Psi$  belongs to  $C^1(\mathbb{R}^d)$  and there exists  $C_\Psi$  such that for all  $x, y \in \mathbb{R}^d$ ,  $\|Q^{-1}(\nabla\Psi(x) - \nabla\Psi(y))\|_Q \leq C_\Psi \|x - y\|_Q$ .

## Geometric convergence of the EI-MALA (I)

We make the following second assumption, which in essence imposes that **the acceptance probability is bounded from below** by a positive constant.

**M2** There exists  $h_\ell \in (0, 2)$  such that for all  $h \in (0, h_\ell]$  there exists three positive real numbers  $a_h$ ,  $R_h$  and  $r_h$  such that for all  $x \in \mathbb{R}^d$ ,  $\|x\|_Q \geq R_h$ ,

$$\inf \{ \alpha_h(x, z), z \in B_Q(\mathcal{O}_h(x, 0), r_h) \} > a_h.$$

## Theorem

Assume **M1**, **M2** and let  $h \in (0, h_\ell \wedge (4/(C_\square^2 + 1)))$ . Then, there exist a distance  $\ell$  on  $\mathbb{R}^d$ ,  $\rho_{\text{EI-MALA}} \in (0, 1)$  such that for all  $x \in \mathbb{R}^d$  and  $n \in \mathbb{N}^*$

$$W_\ell(P^n(x, \cdot), \pi) \leq C\rho^n \{ \mathcal{V}(x) + \mathcal{V}(y) \},$$

with  $\mathcal{V}(x) = 1 \vee \|x\|_Q$ .

## Calculation of the coefficient contraction in a simple case

- To illustrate our bounds, assume that  $\mathbf{M} \equiv 0$  and that  $\mathbf{M}$  is bounded on  $\mathbb{R}^d$  and gradient Lipschitz.
- It is easily checked that **M1** and **M2** are satisfied.
- We can compute the dependence of the contraction coefficient in function of the dimension, and see that this **dependence is polynomial**.

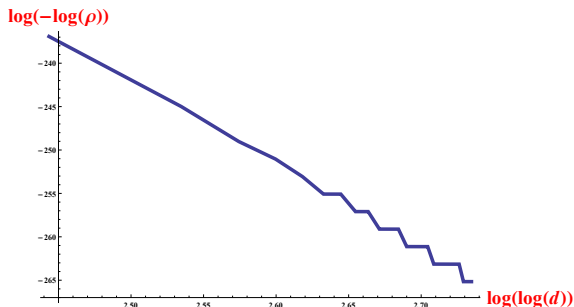


FIGURE: Evolution of the rate of convergence  $\rho_{\text{EI-MALA}}$  in function of the dimension  $d$ .

## Numerical illustrations (I)

We have considered an ill-conditioned Bayesian linear inverse problem.

- It is assumed that the observation  $y \in \mathbb{R}^p$  is given by

$$y = Ax + G$$

with  $G \sim \mathcal{N}(0, I_p)$ ,  $A \in \mathbb{R}^{p \times d}$ , and **we want to learn  $x$** .

- In this problem, the dimension  **$d$  can be very large** and  $p \ll d$ .
- The prior distribution  $\pi_X$  of  $x$  is given to be **a small perturbation of a exponential power distribution** (see [Box and Tiao ,1992]) :

$$\pi_X(x) \propto \exp \left( -\lambda_1 (x^T x + \delta)^\beta - (\lambda_2/2)(x^T x) \right) ,$$

with  $\beta \in (1/2, 1)$ ,  $\lambda_1, \lambda_2, \delta \in \mathbb{R}_+^*$ .

## Numerical illustrations (II)

- In this setting, the posterior distribution  $\pi$  is proportional to  $\exp(-U)$  on  $\mathbb{R}^d$ , where  $\blacksquare = 0$  and the potential  $U$  is on the form

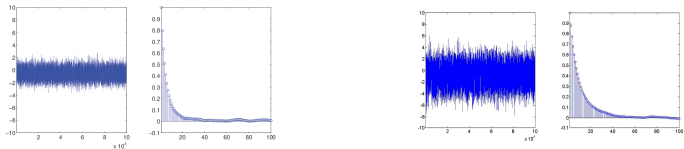
$$U(x) = (1/2)x^T Q x + \blacksquare(x) \text{ with } Q \succ 0,$$

where

$$Q = A^T A/2 + \lambda_2 I_d \text{ and } \blacksquare(x) = \lambda_1 (x^T x + \delta)^\beta - \langle y, Ax \rangle .$$

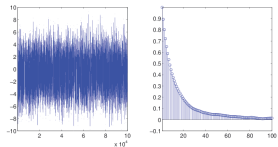
- We can prove that  $\pi$  satisfies **M1** and **M2**.

## Numerical illustrations (II)



:  $d = 100$

:  $d = 500$



:  $d = 1000$

**FIGURE:** Trace plot and auto-correlation in function of the dimension on 10000 iterations with a 10000 burn-in iterations .

## The End

Thank you for your attention !